

## Lecture 6: Robust Estimation

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**Disclaimer:** These notes have not been subjected to the usual scrutiny reserved for formal publications.

## 6.1 Introduction

There are many examples of learning from data. What if not all the data is generated by the model? Consider the case when  $(1 - \epsilon)$  fraction of data points are from the model and  $\epsilon$  fraction are arbitrary (adversarial). Is it still possible to estimate the model parameters?

Low-degree sample moments are not robust estimators. For example,

- Mean: Adding a point really far from the samples will significantly change the mean.
- Singular vectors/eigenvectors: Consider samples with  $e_1$  as the top singular vector. Adding a point  $(0, Me_2)$ ,  $M \gg 1$ , will significantly move the top singular vector.

Consider the problem of estimating a single Gaussian. For a 1-d Gaussian distribution,  $N(\mu, \sigma^2)$ , the median of the sample points,  $\hat{m}$  is a robust estimator of the mean.  $|\mu - \hat{m}| = O(\epsilon)\sigma$  w.h.p. This is the best possible estimate in 1-d. In dimension  $d$ , what is a robust estimate for the mean such that the error does not grow with  $d$ ?

**Tukey Ellipsoid:** Tukey ellipsoid is the minimum volume ellipsoid that contains half of the data points. The center of Tukey ellipsoid is a good estimate for the mean. However, it is NP-hard to compute. [2016] For a large class of distributions, the mean and covariance can be estimated to within error of information theoretic bound.

$$\left\| \Sigma^{-1/2}(\bar{\mu} - \mu) \right\|_2 = O(\epsilon \sqrt{\log(1/\epsilon)}).$$

Two algorithms for robust mean estimation:

1. Iterative Filtering
2. Recursive Dimension Halving

**Lemma 6.1.** For an  $\epsilon$ -corrupted Gaussian,  $N(\mu, I)$  with additive corruptions, if the sample covariance,  $\hat{\Sigma}$  satisfies  $\left\| \hat{\Sigma} \right\|_2 \leq 1 + \epsilon$ , then  $\|\hat{\mu} - \mu\|_2 = O(\epsilon)$ .

*Proof.* Without loss of generality, let  $\mu = 0$ . Let  $S = G \cup B$  where  $G$  is set of samples from the Gaussian and  $B$  is added corrupted points. With enough samples, the sample mean of  $G$ ,  $\mu_G \approx \mu$  and the sample variance of  $G$ ,  $\Sigma_G \approx \Sigma$ .

Let  $\mu_B = \sum_{x \in B} x / |B|$  and  $\Sigma_B = \sum_{x \in B} xx^\top / |B| - \mu_B \mu_B^\top$ . The sample mean  $\hat{\mu}$  and the sample covariance  $\hat{\Sigma}$ , Then

$$\begin{aligned} \hat{\mu} &= \epsilon \mu_B. \\ \hat{\Sigma} &= (1 - \epsilon)I + \epsilon \Sigma_B + (\epsilon - \epsilon^2) \mu_B \mu_B^\top. \end{aligned} \tag{6.1}$$

For  $v = \mu_B / \|\mu_B\|$ ,

$$1 + \epsilon \geq v^\top \hat{\Sigma} v \geq 1 - \epsilon + (\epsilon - \epsilon^2) \|\mu_B\|^2.$$

Therefore,  $\|\mu_B\| \leq 2/(1 - \epsilon) = O(1)$  and  $\|\hat{\mu}\| = O(\epsilon)$ .  $\square$

For general noise,  $\|\hat{\mu} - \mu\| = O(\epsilon\sqrt{\log(1/\epsilon)})$ .

Due to Gaussian concentration,  $\|x - \mu\| \leq C\sqrt{d\log(N/\tau)}$  for all sample points  $x \in G$  w.h.p. So, we can remove all points  $x_i$  with  $\|x_i - \mu\| \geq C\sqrt{d\log(N/\tau)}$ .

**Lemma 6.2.** *After removing all points  $x$  with  $\|x\| \geq C\sqrt{d\log(N/\tau)}$  from the sample,  $\lambda_{\min}(\hat{\Sigma}) \geq 1 - \epsilon$  and  $\text{Tr}\hat{\Sigma} = (1 + O(\epsilon))d$ .*

*Proof.* For any  $v \in \mathbb{R}^d$  with  $\|v\| = 1$ ,  $v^\top \hat{\Sigma} v \geq (1 - \epsilon)$ , therefore  $\lambda_{\min}(\hat{\Sigma}) \geq (1 - \epsilon)$ .

After removing points with  $\|x\|_2 \geq C\sqrt{d\log(N/\tau)}$ ,

$$\begin{aligned} \text{Tr}\hat{\Sigma} &= (1 - \epsilon)d + \epsilon (\text{Tr}\Sigma_B + (1 - \epsilon)\mu_B\mu_B^\top) \\ &\leq (1 - \epsilon)d + \epsilon \sum_{x \in B} \|x\|_2^2 / |B| \\ &\leq (1 - \epsilon)d + \epsilon C^2 d = (1 + O(\epsilon))d. \end{aligned} \quad \square$$

$\lambda_{\min}(\hat{\Sigma}) \geq 1 - \epsilon$  and  $\text{Tr}\hat{\Sigma} = (1 + O(\epsilon))d$  imply  $\lambda_{d/2}(\hat{\Sigma}) = 1 + O(\epsilon)$ . So, in the span of the bottom  $d/2$  eigenvectors of  $\hat{\Sigma}$ , sample mean is a good approximation of the true mean.

**Algorithm 1:** Recursive Dimension Halving

Given corrupted samples  $S$ :

1. Let  $m = \text{coordinate-wise median}(\{x : x \in S\})$ .
2. Remove all points,  $x$  with  $\|x - m\|_2 \geq C\sqrt{d\log(N/\tau)}$  from the samples.
3. Find eigendecomposition of  $\hat{\Sigma}$ . Let  $W$  be the span of bottom  $d/2$  eigenvectors and  $V$  be the span of top  $d/2$  eigenvectors. Then  $\|\hat{\mu}_W - \mu_W\|_2 \leq O(\epsilon)$ .
4. Recurse on  $V$ .

In step 2, we don't know the true mean  $\mu$  but  $\|\mu - m\|_2 \leq O(\epsilon\sqrt{d\log(N/\tau)})$  w.h.p. So, for any point  $x \in G$ ,  $\|x - \mu\| \leq \|x - m\| + \|\mu - m\| = O(\sqrt{d\log(N/\tau)})$ . There are  $\log(d)$  levels of recursion and the total error is  $O(\epsilon\sqrt{\log(d)})$ .

**Idea 2:** Remove points so that  $\|\hat{\Sigma}\|_2$  is close to 1.

Let  $N = |S|$ . Using a union bound, w.p.  $\tau/3$ , for all  $x \in G$  we have

$$\|x - \mu\|_2 = O(\sqrt{d\log(N/\tau)}).$$

The number of samples  $N$  is at least  $\Omega(\frac{d^2}{\epsilon^2} \log(d/\epsilon\tau))$ . Let  $\alpha = \frac{1}{\log(d\log(\frac{d}{\epsilon\tau}))}$ . The next 2 lemmas prove the correctness of Algorithm 2.

**Lemma 6.3.** *If  $\|\hat{\Sigma}\|_2 \geq 1 + C\epsilon\sqrt{\log(1/\epsilon)}$ , then there exists  $v \in \mathbb{R}^d$ ,  $\|v\| = 1$  and  $t > 0$  such that*

$$\Pr_S(|v^\top x - v^\top \mu| > t + 2) > 8e^{-t^2/2} + \frac{8\epsilon\alpha}{t^2}. \quad (6.2)$$

*Proof.* Without loss of generality, let  $\mu = 0$ . Let  $v$  be the top eigenvector of  $\hat{\Sigma}$ . If  $\Pr_S(|v^\top x| > t + 2) \leq 8e^{-t^2/2}$  for all  $t > 0$ , then

$$v^\top \Sigma_B v = \mathbb{E}_B[(v^\top (x - \mu_B))^2] = \mathbb{E}_B[(v^\top x)^2] - (v^\top \mu_B)^2$$

$$\leq 2 \int_{t=0}^{\infty} t \Pr_B(|v^\top x| \geq t) dt = 2 \int_{t=0}^{O(\sqrt{d \log(N/\tau)})} t \Pr_B(|v^\top x| \geq t) dt.$$

We can restrict to  $|v^\top x| \leq \|x\| \leq \sqrt{d \log(N/\tau)}$  after naively pruning. Note that  $\Pr_B(|v^\top x| \geq t) \leq \frac{|S|}{|B|} \Pr_S(|v^\top x| \geq t)$ .

$$\begin{aligned} v^\top \Sigma_B v &\leq 2 \int_{t=0}^{O(\sqrt{\log(1/\epsilon)})} t dt + \frac{2}{\epsilon} \int_{O(\sqrt{\log(1/\epsilon)})}^{O(\sqrt{d \log(N/\tau)})} t \Pr_S(|v^\top x - \mu| \geq t) dt \\ &\leq \log(1/\epsilon) + \frac{16}{\epsilon} \int_{O(\sqrt{\log(1/\epsilon)})}^{O(\sqrt{d \log(N/\tau)})} t e^{-\frac{(t-2)^2}{2}} dt + 16 \int_{O(\sqrt{\log(1/\epsilon)})}^{O(\sqrt{d \log(N/\tau)})} \frac{\alpha}{t} dt \\ &\leq \log(1/\epsilon) + \frac{16}{\epsilon} \int_{O(\sqrt{\log(1/\epsilon)})}^{O(\sqrt{d \log(N/\tau)})} (t-2) e^{-\frac{(t-2)^2}{2}} dt + \frac{32}{\epsilon} \int_{O(\sqrt{\log(1/\epsilon)})}^{O(\sqrt{d \log(N/\tau)})} e^{-\frac{(t-2)^2}{2}} dt + O(1) \\ &\leq \log(1/\epsilon) + O(\epsilon) + O(1) \end{aligned}$$

Using equation (6.1),

$$v^\top \hat{\Sigma} v \leq (1 - \epsilon) + \epsilon \log(1/\epsilon) + O(\epsilon),$$

which is a contradiction.  $\square$

The idea is to remove all points with  $|v^\top x| > t + 2$  from the sample and iterate. The next lemma implies that at least half of the removed points are from  $B$ . In the end,  $\|\hat{\Sigma}\|_2$  is small and at most  $2\epsilon$  fraction of the points are removed.

**Lemma 6.4.** *For all unit vectors  $v \in \mathbb{R}^d$  and  $t > 0$ ,*

$$\Pr_G(|v^\top x - \mu^\top v| > t) \leq 2e^{-t^2/2} + \frac{\epsilon\alpha}{t^2} \quad (6.3)$$

with probability at least  $1 - \tau$ .

*Proof.* Wlog, let  $\mu = 0$ . Let  $\delta = \epsilon\alpha$ . Let  $n = |G| \geq (1 - \epsilon)N$ . We will prove that for any  $v \in \mathbb{R}^d$  with  $\|v\| = 1$  and  $t > 0$ ,

$$|\Pr_G(|v^\top x| > t) - \Pr_{x \sim N(0,1)}(|v^\top x| > t)| \leq \frac{\delta}{t^2}.$$

Since the VC-dimension of the set of all halfspaces is  $d + 1$ , if  $t < \sqrt{C \log(1/\delta)}$ , this bound is true with probability at least  $1 - \tau/3$  if we have more than  $\Omega(\frac{d \log(1/\delta)^2}{\delta^2})$  samples using the VC inequality from [devroye2012combinatorial].

We only need to consider the case when  $t \geq \sqrt{C \log(1/\delta)}$ . Let  $E_i$  denote the event that  $|v^\top x_i| > t$ . Then  $\Pr(E_i) \leq 2e^{-\frac{t^2}{2}}$  and  $E_i$ 's are mutually independent. Note that  $\Pr_G(|v^\top x| > t) = \sum_i 1_{E_i}/n$ . Therefore,

$$\mathbb{E}[e^{\frac{T^2 n}{3} \Pr_G(|v^\top x| > t)}] \leq (1 + e^{-t^2/2} e^{\frac{t^2}{3}})^n = (1 + e^{-\frac{t^2}{6}})^n \leq (1 + \delta^2)^n \leq e^{\delta^2 n}.$$

Using Markov's inequality,

$$\Pr(\Pr_G(|v^\top x| > t) \geq \delta/T^2) \leq \frac{\mathbb{E}[e^{\frac{T^2 n}{3} \Pr_G(|v^\top x| > t)}]}{e^{\frac{\delta n}{3}}} \leq e^{n\delta^2 - \frac{n\delta}{3}} \leq e^{-\frac{n\delta}{6}}.$$

Let  $\mathcal{C}$  be a  $1/2$ -net for unit vectors in  $\mathbb{R}^d$ . Then  $|\mathcal{C}| = 2^{O(d)}$ . From equation ,  $|v^\top x| \leq O(\sqrt{d \log(n/\tau)})$ . Let  $R = c\sqrt{d \log(n/\tau)}$  for some large constant  $c$  and let  $D$  be set of all powers of 2 between  $\sqrt{C \log(1/\delta)}$  and  $R$ . Since  $n = \Omega(\frac{d}{\epsilon} \log(1/\tau))$ , for any  $v' \in \mathcal{C}$  and  $t' \in D$ , with probability at least

$$1 - e^{-\frac{n\delta}{6}} |\mathcal{C}| \cdot |D| \geq 1 - \tau/2$$

we have

$$\Pr_S(|v'^{\top}x| > t') \leq \frac{\delta}{t'^2}.$$

For any unit vector  $v \in \mathbb{R}^d$  and  $t \in [\sqrt{C \log(1/\delta)}, R)$ . Then, there exists  $t' \in D$  such that  $t \leq t' \leq 2t$  and  $v' \in C$  such that  $|v^{\top}x| \leq 2|v'^{\top}x|$ . So,  $|v^{\top}x| > t$  implies  $|v'^{\top}x| > t'$ , and

$$\Pr_S(|v^{\top}x| > t) \leq \Pr_S(|v'^{\top}x| > t') \leq \frac{\delta}{Ct'^2} \leq \frac{\delta}{Ct^2}. \quad \square$$

From equations (6.2) and (6.3), in each iteration, we remove more corrupted than uncorrupted points.

<b>Algorithm 2:</b> Iterative Filtering
<ol style="list-style-type: none"> <li>1. Naively prune points with large norms.</li> <li>2. If <math> \hat{\Sigma} _2 \leq 1 + C\epsilon\sqrt{\log(1/\epsilon)}</math>, output <math>\hat{\mu}</math>.</li> <li>3. Let <math>v</math> be the top eigenvector of <math>\hat{\Sigma}</math> and <math>m = \text{median}(\{v^{\top}x : x \in S\})</math>.</li> <li>4. Find <math>t &gt; 0</math> such that <div style="text-align: center; margin: 5px 0;"> <math display="block">\Pr_S( v^{\top}x - m  &gt; t + 2) &gt; 8e^{-t^2/2}.</math> </div> </li> <li>5. Recurse on <math>S' = \{x \in S :  v^{\top}x - m  \leq t + 2\}</math></li> </ol>



In step 2, we don't know the value of  $v^{\top}\mu$  but  $|v^{\top}\mu - m| \leq O(\epsilon)$  w.h.p. So, for any point  $x \in G$ ,

$$|v^{\top}x - v^{\top}\mu| < |v^{\top}x - m| + |v^{\top}\mu - m| = O(1).$$

## References

- [1] Luc Devroye and Gábor Lugosi. *Combinatorial methods in density estimation*. Springer Science & Business Media, 2012.