

Lecture 4: Nondeterminism and Regular Languages

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### 4.1 Nondeterminism

Example: An NFA is given as follows:

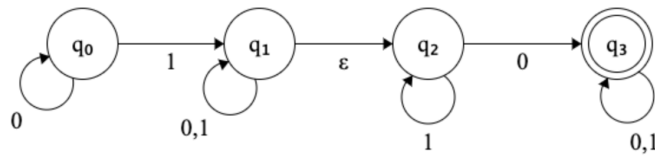


Figure 4.1: An NFA

The regular expression of the NFA is  $0^*1\{0, 1\}^*0\{0, 1\}^*$ .  
 The corresponding DFA is

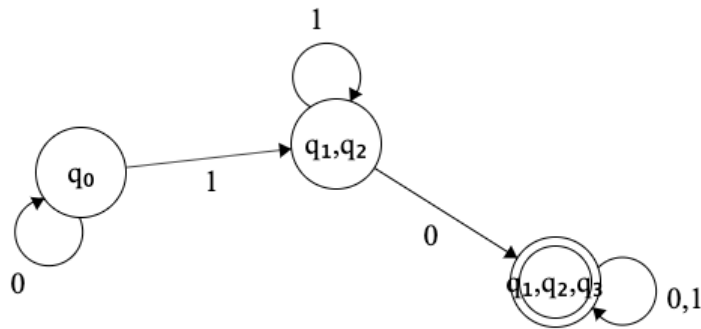


Figure 4.2: A corresponding DFA

**Theorem 4.1** Every NFA can be converted to a DFA.

**Proof:** General construction:

Given a NFA with  $\{Q, \Sigma, \delta, q_0, F\}$ , construct a corresponding DFA  $\{Q', \Sigma', \delta', q'_0, F'\}$  as follows: First, we only consider transitions on symbols.

- $Q' = 2^Q$
- For  $R \subseteq Q$ , i.e.,  $R \in Q'$ ,  $\delta'(R, a) = \{q | \exists q' \in R, \delta(q', a) = q\}$
- $q'_0 = \{q_0\}$
- $F' = \{R \subseteq Q | \exists q \in R \cap F\}$

To add  $\varepsilon$  transition, we define

$$\varepsilon(R) = \{q | q \in R \text{ or } (\exists q' \in R \text{ and } \delta(q', \delta) = q)\}$$

Then we consider  $\varepsilon$  transitions and get “ $\varepsilon$ -extension” of  $R$ :

- $Q' = 2^Q$
- For  $R \subseteq Q$ , i.e.,  $R \in Q'$ ,  $\delta'(R, a) = \varepsilon(\{q | \exists q' \in R, \delta(q', a) = q\})$
- $q'_0 = \varepsilon(\{q_0\})$
- $F' = \varepsilon(\{R \subseteq Q | \exists q \in R \cap F\})$

Hence, every valid sequence of transitions is allowed in the new DFA. All accepting paths remain accepting paths. ■

**Corollary 4.2**  $L$  is regular  $\iff \exists$  NFA that recognizes it.

Nondeterminism is **convenient** but not more powerful.

There are some examples showing the convenience of NFA.

- NFA that accepts  $L_1 \cup L_2$ , where  $L_1, L_2$  are regular languages.

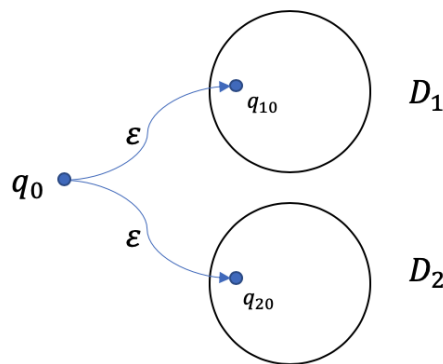
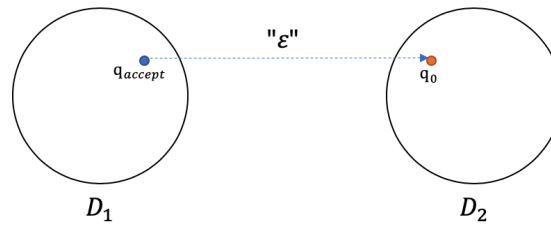
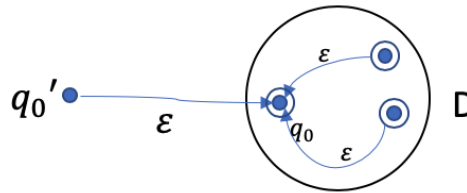


Figure 4.3: NFA that accepts  $L_1 \cup L_2$

- NFA that accepts  $L_1 \cdot L_2 = \{ab \mid a \in L_1, b \in L_2\}$ , where  $L_1, L_2$  are regular languages.

Figure 4.4: NFA that accepts  $L_1 \cdot L_2$ 

- NFA that accepts  $L^*$ , i.e.,  $L = aa, bc$ ,  $L^* = \{\emptyset, aa, bc, aaaa, bcbc, aabc, \dots\}$ .

Figure 4.5: NFA that accepts  $L^*$ 

## 4.2 Regular expressions

### 4.2.1 Definition

Say that  $R$  is a **regular expression** if  $R$  is

- $R = \emptyset$ , empty language
- $R = a, \forall a \in \Sigma$
- $R = \{\varepsilon\}$ , language with empty string
- $R = (R_1 \cup R_2)$ , where  $R_1$  and  $R_2$  are regular expressions
- $R = R_1 \cdot R_2$ , where  $R_1$  and  $R_2$  are regular expressions
- $R = R_1^*$ , where  $R_1$  is regular expression

Example: Describe a regular expression for binary strings with an even # of 1's.

Solution:  $(0^*10^*1)^*0^*$ .

**Theorem 4.3**  $L$  is regular  $\iff \exists$  regular expression for  $L$ .

**Proof:**

First, we prove that for any regular expression  $R$  that represents language  $L$ ,  $L$  is regular. According to 4.2, we just have to show that there is a NFA/DFA that recognizes  $L$ .

Let's convert  $R$  into an NFA  $N$ . We consider the six cases in the formal definition of regular expressions.

1.  $R = a, \forall a \in \Sigma$ . Then  $L(R) = \{a\}$ , and the following NFA recognizes  $L(R)$ .

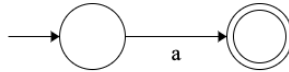


Figure 4.6: NFA that recognizes  $L(R) = a$

2.  $R = \varepsilon$ . Then  $L(R) = \{\varepsilon\}$ , and the following NFA recognizes  $L(R)$ .

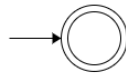


Figure 4.7: NFA that recognizes  $L(R) = \{\varepsilon\}$

3.  $R = \emptyset$ . Then  $L(R) = \emptyset$ , and the following NFA recognizes  $L(R)$ .



Figure 4.8: NFA that recognizes  $L(R) = \emptyset$

4.  $R = R_1 \cup R_2$ . Refer to the previous lecture note.
5.  $R = R_1 \cdot R_2$ . Refer to the previous lecture note.
6.  $R = R_1^*$ . Refer to the previous lecture note.

The other direction is also elementary but more tedious, please refer to the book. ■

## 4.3 Nondeterministic TMs

### 4.3.1 Definition

A nondeterministic Turing machine is defined as a tuple  $(Q, \Gamma, \sigma, F, q_0)$

- $Q$ : A set of states of finite size
- $\Gamma$ : tape alphabet,  $\Sigma \cup \{-\}$
- $\delta$ : list of allowed transitions and can be more than 1 for  $(q, a)$
- $F \subseteq Q$ : set of accepting states
- $q_0$ : the initial state

NTM accepts an input iff  $\exists$  valid computation path leading to an accept state.

**Question:** Is NTM more powerful than TM?

Let's take a look at some examples.

1. Does there exist a path from  $s$  to  $t$  in graph  $G = (V, E)$ ?

Deterministic TM: BFS, DFA

Nondeterministic TM: Guess next vertex! (All edges are valid transitions)

2. Does there exist a Hamilton cycle (visiting all vertices once) in  $G$ ?

3. Does there exist a TSP of length  $\leq L$ , given a graph (map) with edge lengths?

Note: Languages recognized by TMs are called "Recursively Enumerable".

## 4.4 Reference

- Ch 1.2 Nondeterminism, "Introduction to the Theory of Computation"
- Ch 1.3 Regular Expressions, "Introduction to the Theory of Computation"
- Ch 3.2 Variants of Turing Machines, "Introduction to the Theory of Computation"