

Lecture 15: Time and Space

October 28, 2019

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15.1 Introduction

Church-Turing thesis: Any computable function is computable by a Turing machine. Note that it is a hypothesis.

Question: What are the resources available for computation?

- Space
- Time
- Random Bits
- Non-determinism

15.1.1 Space and Time

Definition 15.1 (NTIME) A language L is said to belong to class $\text{NTIME}(t(n))$ if there exists a NTM M that decides L and for input strings of size n , L runs for $O(t(n))$ steps.

Definition 15.2 (DTIME) A language L is said to belong to class $\text{DTIME}(t(n))$ if there exists a TM M that decides L and for input strings of size n , L runs for $O(t(n))$ steps.

Definition 15.3 (NSPACE) A language L is said to belong to class $\text{NSPACE}(s(n))$ if there exists a NTM M that decides L and for input strings of size n , L uses $O(s(n))$ additional space.

Definition 15.4 (DSPACE) A language L is said to belong to class $\text{DSPACE}(s(n))$ if there exists a TM M that decides L and for input strings of size n , L uses $O(s(n))$ additional space.

Note that we do not count input cells in the space used by a TM.

Definition 15.5 (Space-constructible) A function $s : \mathbb{N} \rightarrow \mathbb{N}$ is called space-constructible if $s(n) \geq \log_2(n)$ and there exists a Turing machine that on input 1^n outputs $s(n)$ in binary while using $O(s(n))$ space.

Definition 15.6 (Configuration of a TM) The configuration of a Turing machine M can be completely specified by the 3-tuple

$$\langle \text{Tape Content, State, Head Position} \rangle$$

If we know that a TM M never uses more than $s(n)$ on input of size n , then the number of possible configuration of M while computing on x is at most $|\Gamma|^{s(n)} \cdot |Q| \cdot (s(n) + n)$ as every cell on the tape can have one of Γ tape symbols and the head can be positioned on the input or any of the $s(n)$ cells used by M .

15.2 Space complexity and Savitch's Theorem

Theorem 15.7 $\text{NTIME}(t(n)) \subseteq \text{DTIME}(2^{O(t(n))})$.

Proof: Consider a language $L \in \text{NTIME}(t(n))$ and let N be a NTM that decides L in $O(s(n))$ space. On input x with $|x| = n$, let T_x be the computation tree produced when N computes on x . If $x \in L$, then at depth $t(n)$ at least one of the nodes is a leaf with state q_{accept} and if $x \notin L$, then at depth $t(n)$, all the nodes must be leaves with states q_{reject} . The branching factor of this tree is $b = |Q| \cdot |\Sigma| \cdot 2$, a constant. Hence, T has at most $b^{t(n)}$ nodes. Consider a TM M which performs BFS on this tree starting from q_0 and accepts if it reaches a configuration with state q_{accept} and rejects otherwise. M decides L in $b^{t(n)} = 2^{O(t(n))}$ time. ■
Note that performing DFS would not work because even if N accepts x , there might be a non-deterministic computation path of unbounded depth.

Lemma 15.8 $\text{DTIME}(t(n)) \subseteq \text{DSPACE}(t(n))$.

Because a TM cannot use more space than its run-time as at each step the head moves only one step to the left or the right.

Theorem 15.9 $\text{NSPACE}(s(n)) \subseteq \text{DTIME}(2^{O(s(n))}) \subseteq \text{DSPACE}(2^{O(s(n))})$.

Proof: Consider $L \in \text{NSPACE}(s(n))$ and let M be a NTM that decides L in $O(s(n))$ space. Total number of configurations of with $s(n)$ space is

$$\begin{aligned} \# \text{ configurations} &= |\Gamma|^{s(n)} \cdot |Q| \cdot (s(n) + n) \\ &= 2^{s(n) \log_2(|\Gamma|) + \log_2(|Q|) + \log_2(s(n)+n)} \\ &= 2^{O(s(n) + \log_2(s(n)+n))} \\ &= 2^{O(s(n))} \end{aligned}$$

We will construct a deterministic TM D that decides L in $O(2^{O(s(n))})$ space. For an input x of length n , consider a directed graph $G_x = (V, E)$ where $V =$ set of configurations of M on input x and there is an edge between configurations $C_i, C_j \in V$ if M can go from configuration C_i to configuration C_j in one step. Then x is accepted by M if and only if there exists a path in G_x from C_0 to C_{accept} . We can check the existence of such a path in $O(|V|)$ time by running BFS. ■

Theorem 15.10 (Savitch's theorem) For a function $f : \mathbb{N} \rightarrow \mathbb{R}^+$, where $f(n) \geq n$,

$$\text{NSPACE}(s(n)) \subseteq \text{DSPACE}((s(n))^2)$$

Consider $L \in \text{NSPACE}(s(n))$ and let M be a NTM that decides L in $O(s(n))$ space. We will construct a deterministic TM D that decides L in $O((s(n))^2)$ space. For an input x of length n , consider a directed graph $G_x = (V, E)$ where $V =$ set of configurations of M on input x and there is an edge between configurations $C_i, C_j \in V$ if M can go from configuration C_i to configuration C_j in one step. Without loss of generality, we can assume that the TM M on reaching accept state write 0 on each cell of the tape and moves to head to the leftmost cell. Let's call this configuration C_{accept} . So every time M is in state q_{accept} , it goes to configuration C_{accept} . Then x is accepted by M if and only if there exists a path in G_x from C_0 to C_{accept} .

Given a directed graph $G = (V, E)$ with n vertices and $s, t \in V$, algorithm 1 can decide whether there exists a path from s to t of length k in $O(\log_2(n) \log_2(k))$ space.

So, in G_x , $|V| = 2^{O(s(n))}$. Let $N = |V|$. The maximum length of path between C_0 and C_{accept} is N . So, the space needed to decide whether there exists a path from C_0 to C_{accept} is

$$\begin{aligned} &= \log_2(N) \cdot \log_2(k) \\ &= (\log_2(N))^2 \\ &= (O(s(n)))^2 \end{aligned}$$

15.2.1 Reachability

Given a directed graph $G = (V, E)$ with n vertices and $s, t \in V$, the following algorithm decides whether there exists a path from s to t of length at most k in G .

Algorithm 1: PATH(u, v, k)

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1 if  $u = v$  OR  $\{(u, v) \in E \wedge k \geq 1\}$  then
2   | return YES
3 else
4   | for  $w \in V \setminus \{u, v\}$  do
5     |   | if PATH( $u, w, \lfloor \frac{k}{2} \rfloor$ ) AND PATH( $u, w, \lceil \frac{k}{2} \rceil$ ) then
6       |   |   | return YES
7 return NO

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Let $|V| = n$, then we can store the current intermediate vertex w with $\log_2(n)$ bit. So, the space needed by the algorithm is

$$\begin{aligned}
 &= \log_2(n) \cdot \text{depth of recursion} \\
 &= \log_2(n) \cdot \log_2(k)
 \end{aligned}$$

15.3 References

- Ch 8.1 Savitch's Theorem, "Introduction to the Theory of Computation"